

Practical Eavesdropping and Skimming Attacks on High-Frequency RFID Tokens

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Abstract

RFID systems often use near-field magnetic coupling to implement communication channels. The advertised operational range of these channels is less than 10 cm and therefore several implemented systems assume that the communication channel is location limited and therefore relatively secure. Nevertheless, there have been repeated questions raised about the vulnerability of these near-field systems against eavesdropping and skimming attacks. In this paper we revisit the topic of RFID eavesdropping and skimming attacks, surveying previous work and explaining why the feasibility of practical attacks is still a relevant and novel research topic. We present a brief overview of the radio characteristics for popular HF RFID standards and present some practical results for eavesdropping experiments against tokens adhering to the ISO 14443 and ISO 15693 standards. We also discuss how an attacker could construct a low-cost eavesdropping device using easy to obtain parts and reference designs. Finally, we present results for skimming experiments against ISO 14443 tokens.

Keywords: RFID, eavesdropping, skimming, contactless smartcard

1 Introduction

High-frequency RFID tokens, using near-field channels, are used to store valuable information in cashless payment systems and even travel documents. No physical contact needs to be made with the reader, which simplifies operation and increases overall transaction speeds. A growing security concern with RFID devices is the possible release of the user's personal information, or location, to unauthorized parties. For example, some consumer groups have rallied against the 'big brother' potential of RFID technology [30]. As RFID tokens are also used for transactions of increasing value, they could become the target of lone opportunistic attackers, who, if able to gain access to the information on the RFID token, might be able to engage in the act of 'digital pick-pocketing' while just standing next to the victim. The two main attacks usually considered are skimming and eavesdropping.

Eavesdropping and skimming attacks are a well known risk for RFID devices and there are several claims about the possibility of these attacks on RFID tokens, for example [31]. The distances at which these attacks are possible are often debated and used as an indication of RFID security, for example [26], so this is an important factor when considering the threat model for RFID devices. Despite this interest, few publications provide enough details about possible experimental setup or practical results. In this paper we discuss the implementation of eavesdropping and skimming attacks on HF RFID and present some practical results for eavesdropping on systems using the ISO 14443A/B and ISO 15693 standards, along with results from a skimming attack using two

separate transmitting and receiving antennas. In each case we provide a detailed explanation of the experimental method and description of the setup. Our main contribution is to provide a reference experimental setup for RFID eavesdropping and skimming attacks to provide a better understanding of the attack’s physical constraints as opposed to theoretical simulation. This would hopefully allow system designers to comprehend the eavesdropping threat in order to select appropriate technologies and countermeasures. Finally, I also discuss how an attacker with limited resources could construct and eavesdropping receiver.

2 Attack scenarios

One of the security concern with RFID devices is the possible release of the user’s personal information, or location, to unauthorized parties. The two obvious ways in which information can be released to an unauthorized party are skimming and eavesdropping, as shown in Figure 1. In most cases the attacker can execute these attacks from further than the operational range, which is the distance at which the system is expected to communicate. In each attack case there are different scenarios, resulting in different attack distances [16].

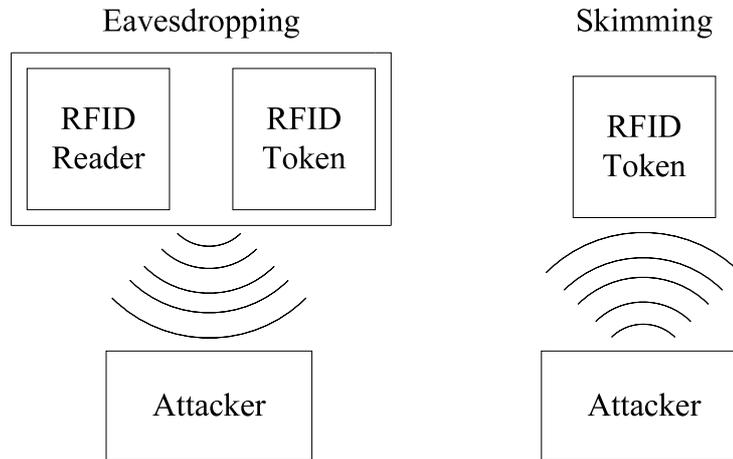


Figure 1: Eavesdropping and skimming attacks

Skimming occurs when the attacker uses his reader to access information on the victim’s RFID token without consent. The attacker has the ability to read stored information or to modify information by writing to the token, so he can control when and where the attack is performed. In practice the attacker’s main challenge is to increase the operational range by powering and communicating with the token over a greater distance, as the owner might become suspicious of somebody in his personal space. In this attack there are two distances to consider:

- The distance at which an attacker can power the token and issue a command.
- The distance at which an attacker can power the token, issue a command and recover a response.

Eavesdropping occurs when the attacker intercepts communication between an RFID token and an authorized reader. The attacker does not need to power or communicate with the token, so he is able to execute the attack from a greater distance than is possible for skimming. He is, however, limited in terms of location and time window, since he has to be in the vicinity of an authorized reader when a transaction that he is interested in, is conducted. In the HF RFID standards the communication schemes used for reader-to-token (forward channel) and token-to-reader (backward channel) are different. As a result the distances at which an attacker can recover the data sent on the forward and backward channels differ. There are three distances to consider for this attack:

- The distance at which an attacker can detect a transaction, i.e. he can see activity on the forward channel but cannot reliably recover the actual data.
- The distance at which an attacker can reliably recover the data sent on the forward channel.
- The distance at which an attacker can reliably recover the data sent on the backward channel.

We assume that an eavesdropping attack is successful when the attacker can reliably recover both the forward and backward channels. Eavesdropping and skimming attacks are described in more detail in Sections 3 and 4.

2.1 Related work

Eavesdropping and skimming attacks are not new and are mentioned regularly in the literature. Recent reports by the National Institute of Standards and Technology (NIST) [21], the Department of Homeland Security (DHS) [6] and the German Federal Office for Information Security (BSI) [3], along with academic surveys, e.g. [16], all mention scenarios for eavesdropping and skimming attacks in the RFID environment. These reports, however, do not show practical results or fail to clarify the experimental setup if they do.

Different scenarios exist for eavesdropping and skimming attacks and therefore the experimental setup should be known in order for published results to be useful. In earlier reports terms used to describe the attacks were also confusing. A report on ‘Port of Entry’ tests done in 2004 [7] states that signals from e-passport systems could be ‘detected’ at 20 m. The report does not explain whether this implies that the attacker could detect that a transaction occurred, or whether he could recover the actual data. The test also covered a number of different systems and no details were given about which system yielded the result. There were also press reports that NIST eavesdropped the RFIDs to be used in USA passports from as far away as 9 m [36]. Reports, however, often used the term ‘read’, which implied a skimming attack, while they were actually describing eavesdropping. There are also cases where reports do not state clearly which type of token they were referring to when describing attack distances. RFID is a collective term for several systems and in reality refers to devices adhering to a number of different standards. An high-frequency(HF) token used for a contactless smart card is not the same as a ultra-high frequency (UHF) tokens used in logistics, which is intended to be read from much greater distances. Therefore, if somebody can read a razor’s tag from 1 m it cannot be assumed that the same is true for an e-passport. It is therefore important to clearly state the type of RFID system when describing these attacks. Yet the American Civil Liberties Union (ACLU) demo, where a ‘passport’ was read from 1 m, used ‘similar’ RFID technology and not an ISO 14443 token as used in a real e-passport [26]. A more recent example of confusing reporting with regards to RFID technology came about when a practical attempt at exploiting possible vulnerabilities [50] in USA ‘PASS’ cards (used for travel between Mexico, Canada, USA and Bermuda as part of the Western Hemisphere Travel Initiative) and enhanced drivers licenses, which use UHF technology, was reported in the popular press as an attack on e-passports [51], which uses HF RFID tokens and different security mechanisms.

Early work on this topic took the form of short, work-in-progress reports released by researchers from both government [8] and academic institutions [10] on ISO 14443A cards in 2005 and 2006 respectively. These reports demonstrated that eavesdropping on HF RFID systems was possible but did not describe the experiments in great detail. Riscure, a Dutch security company, later claimed that it was possible to eavesdrop the backward communication at a distance of 5 m, and the forward channel at a distance of 25 m [31]. They have, however, not actually implemented the attack. In 2006 Kirschenbaum and Wool demonstrated and documented a skimming attack on ISO 14443A tokens at a distance of 25 cm [37]. They used a loop antenna with a diameter

of 40 cm to power and read a card. In the same year Flexilis demonstrated a skimming attack for 21 m on a UHF [40] system. At the end of 2006 NIST published a report [9], which was reported in [21], to show that ISO 14443 tokens could be eavesdropped at 15 m. This report, however, did not describe the experiment environment or the details of the receiver used. NXP published a report on eavesdropping and skimming ranges in 2008 [35], which describes the theoretical limits for eavesdropping and skimming distances taking into account three signal to noise scenarios: 'business', 'residential' and 'rural'. This report does not provide much detail on practically implementing these attacks but based on their calculation the skimming distance of ISO 14443 systems is limited to approximately 30 cm, and eavesdropping under normal conditions ('business') should be possible to 3.5 m.

Several other research papers describe practical projects regarding HF RFID, which require that the system receives RF communication, although none of these can be said to have implemented an eavesdropping attack [38,39]. A number of published security protocols make the assumption that the data transmitted from the token to the reader is secure, or more so than the data transmitted by the reader to the card [41].

2.2 Significance

The recovery of useful data by eavesdropping can be prevented by encrypting the transmitted data, and skimming attacks can be prevented by implementing suitable authentication mechanisms. Most HF RFID tokens are basically contactless smart cards, which can easily cope with implementing application layer security. So why are these attacks still important? In earlier systems near-field communication was seen as secure because the specified operational range was seen to be limited and as a result several weak security measures were implemented. This section briefly discusses two security sensitive RFID applications and their perceived weaknesses soon after deployment.

Credit cards: New contactless payment systems, of which the majority adhere to ISO 14443A, are in widespread use today. Plans have also been put forward where an ISO 18092 enabled device, such as a mobile phone or PDA, acts as a contactless credit card [46]. RFID credit cards have, however, been used in the USA since 2003, where these are also implemented using the ISO 14443B communication standard. Not enough information is currently available to comment on the new contactless payment systems, but an academic study has shown there to be a number of vulnerabilities in the first generation of USA credit cards [11]. User and banking information were often sent in plaintext between the reader and the RFID-enabled cards. An attacker could also retrieve the data by implementing a skimming attack and the information transmitted on the RF channel was allegedly sufficient to imitate a valid card.

e-Passports: By 26 October 2006 the USA required that 27 countries issue their citizens with e-passports in order to still qualify under the Visa Waiver Program. E-passports adhere to operational specifications as defined by the International Civil Aviation Organisation (ICAO) [12] and use the ISO 14443 standard. ICAO allows for optional security protocols, such as Basic Access Control (BAC), that provides both authentication and encryption services. BAC derives a key from the passport serial number, expiry date and the user's birthday, read off the OCR strip inside the passport. The idea is that anyone presented with the passport can read the OCR data, derive the key and retrieve the data off the RFID token inside. Security problems of this scheme have been pointed out [17], especially with the effective size of the key. Theoretically the data can be used to generate a key with an effective length of at least 50 bits [52]. Predictability in the data could however decrease the effective key length to 35 [31] or even 27 [17] bits, which makes a brute force key search attack feasible. This implies that an attacker could eavesdrop communication between a passport and reader and try to decrypt it at a later stage exploiting this weakness in the key. In this case skimming attacks are more difficult, since the attacker would need access

to the passport until he finds the correct key by repeatedly running the authentication protocol. It might, however, be feasible that an attacker can gain access to the passport while in the mail and attempt to read the data without breaking the seal on the envelope, especially when the attacker already knows some of the information used to generate the key. For example, some serial numbers are sequential and the expiry date has to occur within a known time window so an attacker can reduce the range of these values. An overview of the latest issues regarding e-passports is presented in [2]. Although it might be infeasible to achieve brute force recovery of keys during a true skimming attack, as the window of opportunity for skimming is short, an attacker could use skimming to trace individual passports, as described in [47]. Some passports contain shielding, which works on the principle of a Faraday cage. Although this approach would hinder skimming, the attacker would still be able to passively eavesdrop when the shielding is removed during legitimate reader-to-token communication.

Travel and Access Control Tokens: HF RFID tokens are also used in a number of travel and access control systems. Recently, the proprietary Crypto1 cryptographic algorithm used in NXP’s Mifare Classic product range was reverse engineered and published [24]. Further analysis of this cipher revealed cryptographic vulnerabilities that could be exploited to recover key material in a matter of minutes [5] [43]. An attacker wishing to execute some of these attacks, however, first need to reliably eavesdrop transactions between a legitimate card and legitimate reader. In the past year, several further attacks were published that only needed access to a legitimate token [49] [48]. It is feasible that these logical attacks could be combined with skimming to retrieve key and product information from user’s cards.

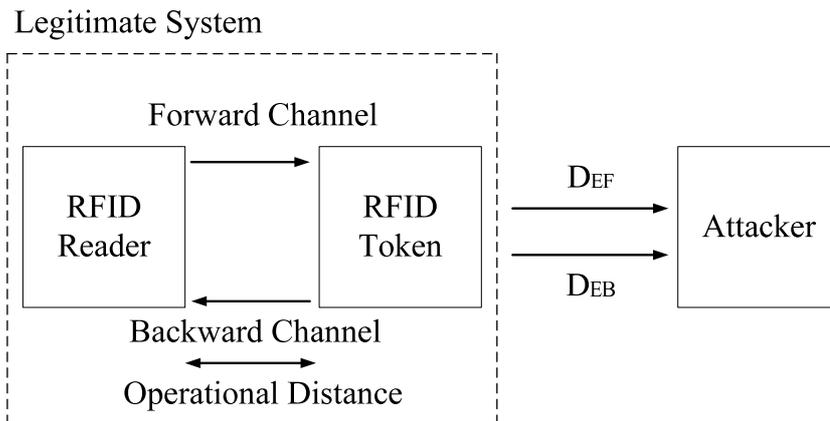


Figure 2: Different distance parameters of a passive eavesdropping attack

3 Eavesdropping

An eavesdropping attack occurs when an attacker can recover the data sent during a transaction between a legitimate reader and a token, which requires the attack to be set up in the vicinity of a likely target. The attacker needs to capture the transmitted signals using suitable RF equipment before recovering and storing the data of interest. The degree of success that the attacker will achieve depends on the resources available to him. An attacker with expensive, specialized RF measurement equipment will be able to eavesdrop from further away than an attacker with a cheap, home-made system. The attack is still a viable threat either way. An opportunistic attacker could possibly recover the credit card details of the person standing in front of him at the cashier if he had a small, portable system that could eavesdrop at 50 cm. Alternatively, if the attacker is able to successfully eavesdrop the communication from 10 m he could sit in a vehicle outside his local corner store and record all the transactions conducted inside.

As we mentioned earlier there are different eavesdropping distances to consider. Near-field communication generally uses different modulation schemes for the forward channel (reader→token) and the backward channel (token→reader). This means that the eavesdropping ranges for each of these channels are different. We therefore define D_{EF} as the distance at which the forward channel can be observed and D_{EB} as the distance at which the backward channel can be observed. The data transmitted depends on the specific application but the attacker is typically more interested in the backward channel. The exceptions are when an attacker simply wishes to determine whether a transaction took place, in which case he only needs to recover the channel with the greatest eavesdropping distance, or when information on the weaker backward channel is echoed on the stronger forward channel. For the purpose of our work we assume an eavesdropping attack to be successful at a certain distance when both the forward and backward channels can be observed at this distance.

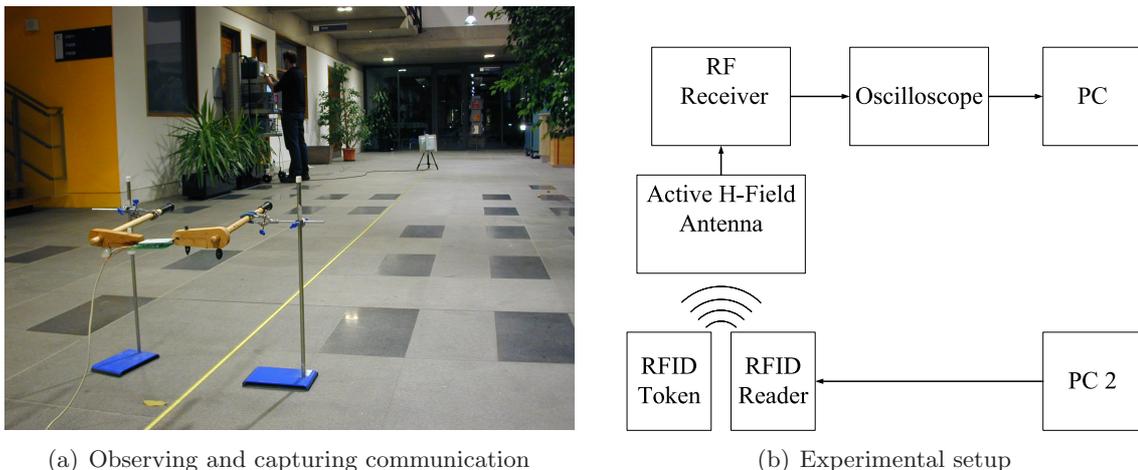


Figure 3: Setup for the eavesdropping experiment

3.1 Experimental setup

We set up a simple eavesdropping attack as shown in Figure 3. The reader and the token were placed in clamps and the antenna positioned at the same height on a tripod so that all three loops were in the same horizontal plane. The antenna, which was connected to the RF receiver, was kept stationary while the reader and token were moved further away. Data signals from the receiver were captured using an oscilloscope and read into Matlab where further DSP functions were performed to recover the data. It should be noted that a number of factors, as discussed later in this section, affect the results of an eavesdropping attack. As a result this work is not about establishing a maximum eavesdropping distance but rather about practically implementing a proof-of-concept attack using a documented method that can be re-created by other researchers to obtain comparable results for their specific environment.

3.1.1 Equipment

There are commercial RF receivers available that can be used to demonstrate the eavesdropping attack. We used the R-1250 Wide Range Receiver and the R-1150-10A Portable Antenna Kit, both manufactured by Dynamic Sciences. The R-1250 is a superheterodyne receiver operating from 100 Hz to 1 GHz with 21 selectable bandwidths, increasing in steps of 1-2-5 from 50 Hz to 200 MHz, centered around 200 kHz or 30 MHz IF frequencies. The receiver allows the user to adjust the RF and pre-detection gain over 50 dB and 30 dB respectively. The user can then

choose whether to use the AM, FM or IF output available. Detailed information about the R-1250 receiver, including calibration data for the specific receiver used in the attack, can be found in [19, pp 23–33]. The antenna kit includes a set of H-field ferrite core antennas for field-strength measurements in the 100 Hz to 30 MHz range. Looking at the H-field is of particular interest when taking into account the dominance of the H-field in the near-field of loop antennas. The receiver is shown in Figure 4(a) and the antenna can be seen in Figure 4(b).



(a) RF receiver [19]



(b) Active H-field antenna

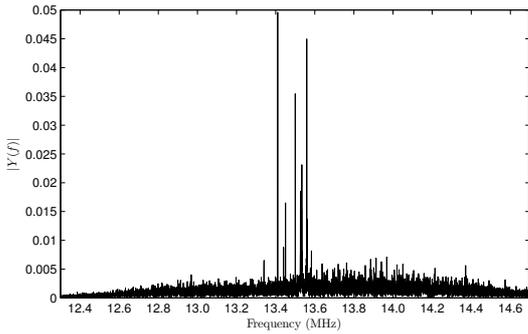
Figure 4: Commercial RF testing equipment

Currently there are three popular standards for passive near-field devices operating at the frequency of 13.56 MHz: ISO 14443A, ISO 14443B and ISO 15693. Since each standard has a different communication scheme it would not suffice to make claims about eavesdropping HF devices without investigating all the standards.

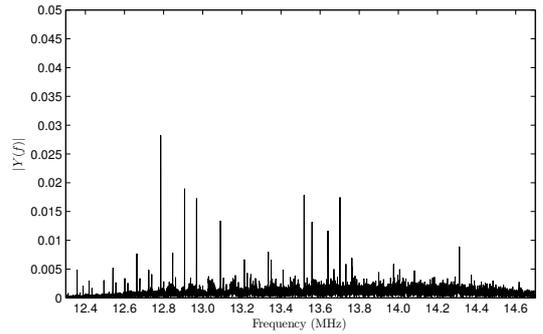
For the eavesdropping experiment we used the ACG Multi-ISO RFID Reader (Antenna dimension: 9 cm × 6 cm). We then used the following tokens: NXP Mifare Classic [23] for ISO 14443A, contactless credit card for ISO 14443B and NXP I-Code [22] for ISO 15693. We would like to point out that we used these products because they were good examples of different HF systems implemented today using the three main HF RFID standards. We do not wish to imply that any of these products are more at risk of eavesdropping than another comparable product.

3.1.2 Environment

It is expected that the magnitude of the H-field will decrease rapidly in the near-field, $d \leq \lambda_{fc} \cdot \frac{1}{2\pi} \approx 3.5$ m, proportionally to $\frac{1}{d^3}$. At larger distances the decrease in the H-field will be proportional to $\frac{1}{d^2}$. The eavesdropper requires a favourable signal-to-noise ratio (SNR) to recover the data. The nature of the background noise will therefore affect the eavesdropping distance. This experiment was not performed in an empty, shielded chamber but in a laboratory that houses equipment that might emit RF signals, or contain metal, which could interfere with the magnetic field originating from the reader. Figure 5 shows the frequency characteristics of the background noise for two possible eavesdropping locations: The main entrance hallway of the Computer Laboratory and the corridor outside our group’s hardware laboratory. The average power of the input signal to the receiver in both cases is approximately -86.5 dBm. One obvious difference between the environments that we would like to comment on is the spectral peaks



(a) Main entrance hall



(b) Hardware lab corridor

Figure 5: Comparative frequency-domain representations of background noise in two locations (RF Receiver: $f_c=13.56$ MHz, BW = 2 MHz)

around 13.5 MHz that can be observed in Figure 5(a), which is most likely the result of several ISO 14443 door access control readers located at regular intervals throughout the entrance hallway.

Apart from the background noise there are several other practical factors influencing the eavesdropping environment. The antenna size and transmitted power depend on the specific reader used in a system. At the same time the coupling between the token and reader also influences the eavesdropping distance as it affects the carrier amplitude and the modulation index of the backward channel. These variations are not easy to quantify since any loop antenna or oscilloscope probe used to measure these values will also influence the system. Similarly, the orientation and the proximity of the card to the reader can also affect the eavesdropping range [9].

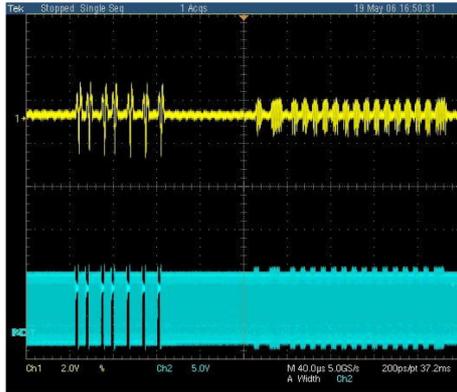
3.2 Method

The main goal of our experiment was to show that eavesdropping on HF RFID devices are possible at non-trivial distances. As mentioned already there are multiple environmental variables to consider. Since it was not feasible to try all possible variations we limited our experiment to a single reader and three tokens adhering to different operating standards. Secondary goals were to determine to what extent the different modulation schemes influenced the eavesdropping range and to investigate whether data could be reliably recovered from a recording with a low SNR. The experiment was repeated in two different locations as discussed in the previous section.

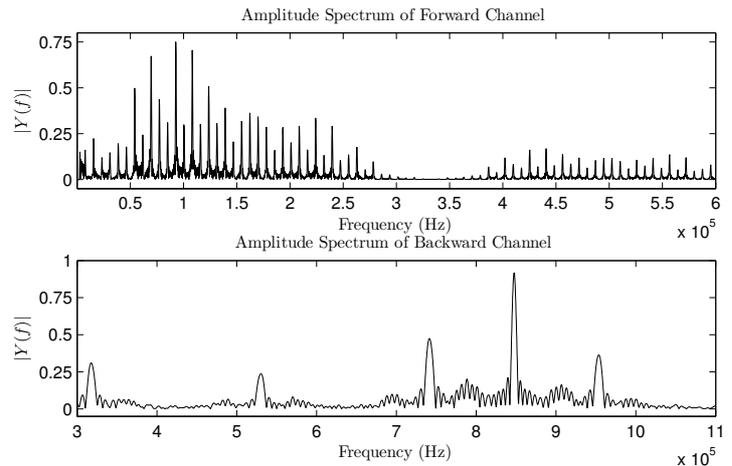
3.2.1 Reference data

The first step of the eavesdropping experiment was to generate a set of reference data for later comparison to the recovered data, and to identify the frequency bands of interest. To generate reference data we required a transaction where the data transmitted on the forward and backward channel was repeatable. The standards in question all have a command instructing the token to return a unique identifier, which was ideal as the data always stayed the same. We recorded the signal at the antenna of the reader and demodulated it to obtain the reference data. We also computed the frequency spectrum for the forward and backward channels using the Fast Fourier Transform (FFT) of this data. When the data were still modulated onto the HF carrier the origin of the calculated spectrum will shift to 13.56 MHz.

ISO 14443A: The reader transmits 106 kbit/s Modified Miller encoded data using 3 μ s pulses. The forward channel data should therefore be in the first 330 kHz of the spectrum. The token



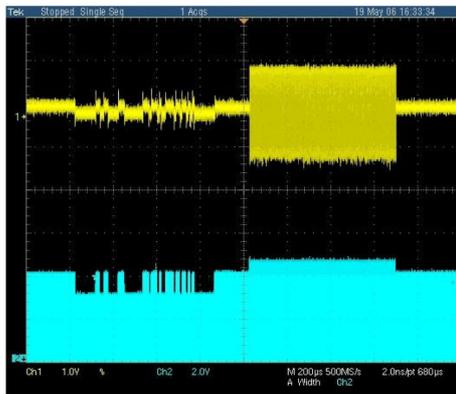
(a) Time domain: Forward (left) and backward (right) channels



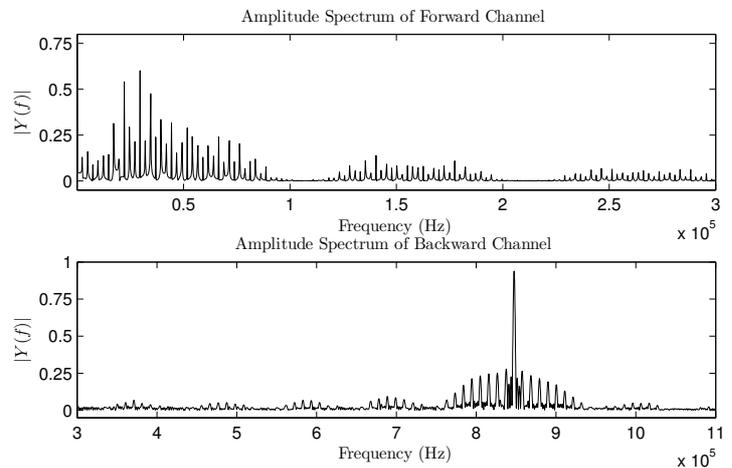
(b) Frequency domain after the 13.56 MHz carrier has been removed

Figure 6: ISO 1443A communication

transmits 106 kbit/s Manchester encoded data, which is ASK modulated onto a 847 kHz subcarrier. The backward channel should be in a 424 kHz band centered around 847 kHz. The forward channel is amplitude modulated onto the 13.56 MHz carrier with a modulation index of 100%, while the backward channel has a modulation index of 8–12%. Figure 6 shows the modulated carrier, the AM demodulated output of the RF receiver and the relevant single-sided frequency spectra for a communication sequence example.



(a) Time domain: Forward (left) and backward (right) channels



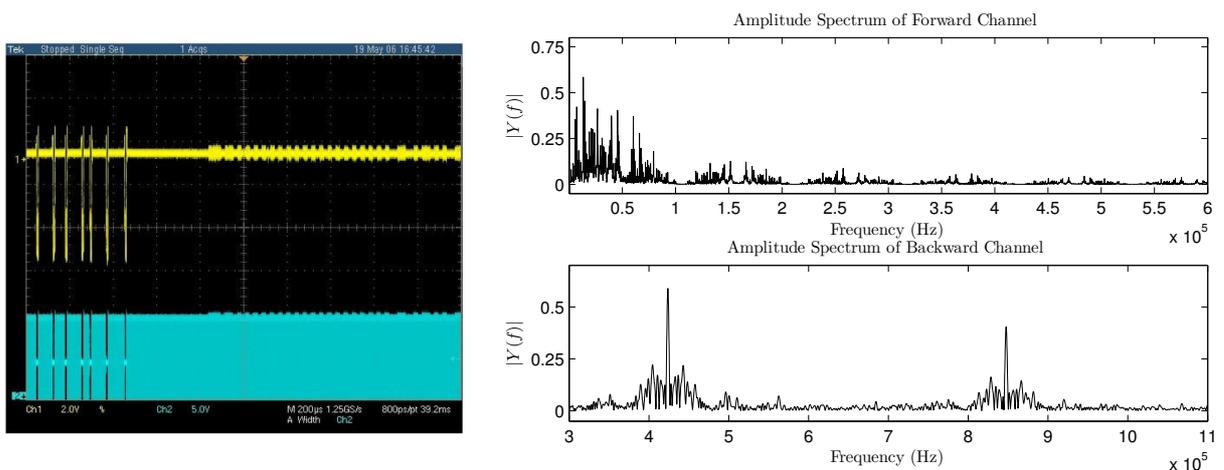
(b) Frequency domain after the 13.56 MHz carrier has been removed

Figure 7: ISO 1443B communication

ISO 1443B: The reader transmits 106 kbit/s NRZ encoded data. The forward channel data should therefore be in the first 106 kHz of the spectrum. The token transmits 106 kbit/s NRZ encoded data, which is BPSK modulated onto a 847 kHz subcarrier. The backward channel should be in a 212 kHz band centered around 847 kHz. The forward channel is amplitude modulated onto the 13.56 MHz carrier with a modulation index of 10%, while the backward channel has a modulation index of 8–12%. Figure 7 shows the modulated carrier, the AM demodulated output of the RF receiver and the relevant single-sided frequency spectra for a

communication sequence example.

ISO 15693: The reader uses a ‘1 of 4’ PPM code with a $9.44 \mu\text{s}$ pulse to transmit 26.48 kbit/s data. The forward channel data should therefore be in the first 106 kHz of the spectrum. The token transmits 26.48 kbit/s NRZ encoded data, which is ASK modulated onto a 423 kHz subcarrier. The backward channel should be in the 53 kHz band centered around 423 kHz. The forward channel is amplitude modulated onto the 13.56 MHz carrier with a modulation index of 10%, while the backward channel has a modulation index of 8–12%. Figure 8 shows the modulated carrier, the AM demodulated output of the RF receiver and the relevant single-sided frequency spectra for a communication sequence example.



(a) Time domain: Forward (left) and backward (right) channels

(b) Frequency domain after the 13.56 MHz carrier has been removed

Figure 8: ISO 15693 communication

3.2.2 Capturing and calibration

The second step was to capture the signals with the RF receiver and record them on the oscilloscope. During early experiments [10] we triggered the oscilloscope on the serial communication between the host PC and the reader. We later decided to change this method as it was not an accurate reflection of an attacker’s actions. There was also a possibility that the additional cables connected to the reader could aid signals of interest to radiate, thereby providing an inaccurate result. Instead we captured the 30 MHz IF output of the RF receiver for a duration of 320 ms at a sampling frequency of 100 MS/s, while the reader was continuously querying the token’s identifier. For each eavesdropping scenario we made two captures, the first with the receiver’s center frequency and bandwidth set to 13.56 MHz and 2 MHz respectively and the second with the center frequency set to the applicable sideband, 14.4 MHz and 13.98 MHz, with bandwidths of 500 kHz and 200 kHz respectively.

The RF gain of the receiver is adjusted by turning a knob, which does not provide an accurate indication of the actual gain introduced. The relative gain of the receiver was therefore measured before each sequence capture. This was done by providing a reference signal, a center-frequency sine wave, as input to the receiver. Its power in dBm was then adjusted until the receiver’s output corresponded to a chosen value on the oscilloscope: 224 mV root-mean-square for the 30 MHz IF output signal, which is approximately 0 dBm. This gain value can then be used to determine the power of the corresponding input from the antenna to the receiver.

3.2.3 Data recovery

The final step is to recover the data from the recorded signal. The SNR of the data decreases with distance and eventually the data can no longer be verified visually, or recovered with a simple threshold function such as a comparator with hysteresis. This does not mean that the data is lost, but that recovery requires further processing to limit the effect of the noise. A common way to reduce the effect of noise is to average several recordings of the same signal. We do not consider this option, because the attacker does not have multiple recordings as the transaction is run only once. A number of receivers optimized to recover signals corrupted by Additive White Gaussian Noise (AWGN) have been proposed, such as the correlation or matched-filter receivers [28, pp 233–244]. The correlation receiver uses N correlators, which projects the received signal $r(t)$ onto N base functions $f_k(t)$.

$$y_k = \int_0^T r(t)f_k(t)dt, \quad k = 1, 2, \dots, N$$

The matched filter receiver uses N linear filters with impulse response $h_k(t) = f_k(T - t)$, to achieve a similar output.

$$\begin{aligned} y_k &= \int_0^t r(\tau)h_k(t - \tau)d\tau \\ y_k &= \int_0^t r(\tau)f_k(T - t + \tau)d\tau \\ y_k &= \int_0^T r(\tau)f_k(\tau)d\tau, \quad k = 1, 2, \dots, N \end{aligned}$$

It should be noted that if the base function is rectangular then $f_k(t) = f_k(T - t)$ for the matched filter. In this case the correlator also becomes an integrator.

$$y_k = \frac{1}{\sqrt{T}} \int_0^T r(t)dt,$$

We used a correlation receiver to recover data from the stored noisy signal. For each of the standards' forward and backward channels $N = 1$ and the base function is rectangular. The only important parameter is T , which was assigned the following values:

- ISO 14443A: Forward channel $T = 3 \mu\text{s}$, backward channel $T = \frac{1}{212 \text{ kHz}} = 4.72 \mu\text{s}$.
- ISO 14443B: Forward channel $T = \frac{1}{106 \text{ kHz}} = 9.44 \mu\text{s}$, backward channel $T = \frac{1}{106 \text{ kHz}} = 9.44 \mu\text{s}$.
- ISO 15693: Forward channel $T = 9.44 \mu\text{s}$, backward channel $T = \frac{1}{52.96 \text{ kHz}} = 18.88 \mu\text{s}$.

An example for recovering the data on the backward channel for ISO 14443A is shown in Figure 9. The process is as follows: (a) is the noisy signal, (b) is the data after it has been filtered using Finite Impulse Response (FIR) filters. The next step is to demodulate the sub-carrier. For ASK we rectified the signal shown in (c) before correlating it with the base function. (d) is the correlator output, which is then sampled to obtain the Manchester encoded data (e). The Manchester data is decoded to NRZ and compared to the reference data. The ISO standards define a strict bit-period grid, relative to the last bit sent by the reader, in which the token's response must be sent. The sampling times can therefore be derived from the forward channel data. Alternatively, a clock recovery scheme as described in [19, pp 125] can be implemented. The attacker can use known data, e.g. *ATQA* and *SAK* responses, to optimize his sampling thresholds, etc.

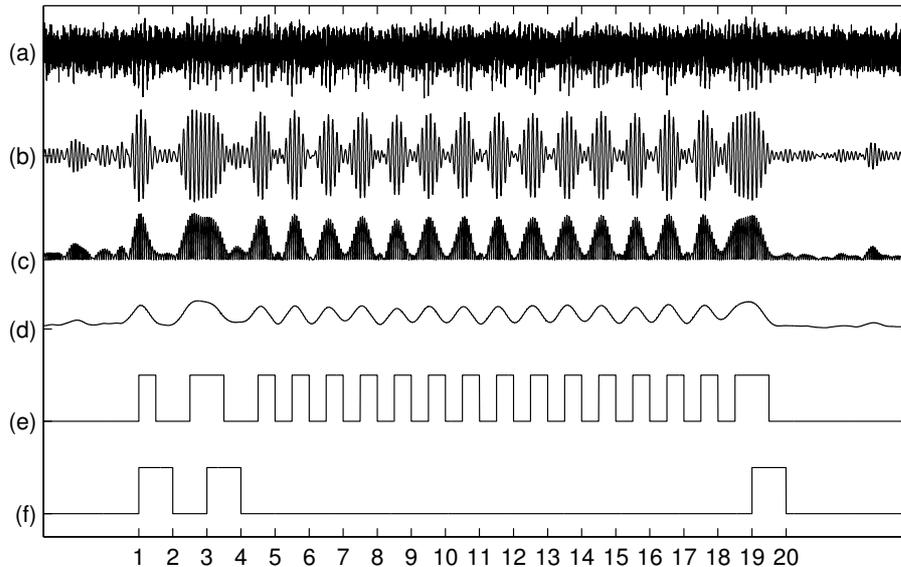


Figure 9: Recovering the data from a noisy signal

3.3 Results

Before presenting our results we first discuss the details of the eavesdropping test described in [9]. This test uses a NXP Pegoda ISO 14443A reader and seven different ISO 14443A tokens from 4 manufacturers. The authors use a matched loop antenna and a ‘receiver system’ (unspecified whether commercial equipment or custom build) in addition to an oscilloscope and a protocol analyser to capture a token’s ID. A high level functional diagram of the receiver is provided but no details are given about the filters, amplifiers and IF sections shown. An eavesdropping attempt is considered successful when the receiver’s output has a SNR greater than 6 dB, which is the level needed by the protocol analyser to obtain the correct ID. The experiment is performed with two different antenna setups: All three loops centered around the same horizontal axis, which resulted in eavesdropping distances of 5–6.5 m, and all three loops in the same horizontal plane, the same as our setup, which resulted in eavesdropping distances of 8–15 m. The fact that seven tokens, adhering to the same standard and communicating with the same reader, yield different results is a good example of how eavesdropping distances vary depending on the specific system components.

Our results are shown in Table 1. Even with additional signal processing we did not manage to achieve the distances in [9], although our results for ISO 14443A tokens are similar to those presented in [8] and appears to follow the theoretical model for a ‘business’ environment give in [35]. There are, however, some interesting conclusions. The forward channel of the ISO 14443A and ISO 15693 communication can be eavesdropped at a much greater distance than the backward channel, but for ISO 14443B D_{EB} is greater than D_{EF} . In addition, it is once again shown that results can vary for different locations since the ISO 14443B forward channel and ISO 14443A backward channel could be recovered in one location, but not the other.

There is still scope for further work on RFID eavesdropping, such as testing different readers and developing better data recovery methods. We started doing some preliminary work on testing how the tuning of the reader and the token affects the eavesdropping range. We placed the antenna 1 m away from the reader and displayed the AM demodulated output of the RF receiver on the oscilloscope. By changing the parallel tuning capacitor value on the reader the amplitude of the backward channel data recovered by the receiver could be largely reduced. This also decreases the operational distance, although this might be an acceptable sacrifice to limit

	ISO 14443A	ISO 14443B	ISO 15693
Entrance hall			
1 m	FB	FB	FB
2 m	FB	FB	FB
3 m	Fx	xB	Fx
4 m	Fx	xx	Fx
5 m	Fx	xx	Fx
Lab corridor			
1 m	FB	FB	FB
2 m	FB	FB	FB
3 m	FB	FB	Fx
4 m	Fx	xB	Fx
5 m	Fx	xx	Fx

Table 1: Eavesdropping results: F – Forward channel recovered, B – Backward channel recovered.

the risk of eavesdropping.

Finally, it is interesting to note that the ISO 18092 “Near-Field Communication (NFC)” standard prescribes the same modulation scheme as ISO 14443A. Devices can operate in *passive* mode, where one device acts as a reader and the other as a token, as well as in *active* mode, where both devices act like a reader. In *active* mode the devices take turns to transmit data using 100% ASK modulation of their respective carriers, effectively creating a ‘forward’ channel in both directions. Such a system could possibly be more vulnerable to eavesdropping, since the eavesdropping distance would be equal to D_{EF} .

3.4 Eavesdropping attacks in the real world

An attacker can execute an eavesdropping attack if he acquired a suitable antenna, an RF receiver and a method to sample and record the data. Even though we illustrated the eavesdropping attack using commercial RF equipment we also want to point out that these attacks can work outside ‘laboratory conditions’ with cheap and portable hardware.

3.4.1 Receiver

The RF receiver converts the modulated HF carrier to a chosen IF after which the signal is filtered to isolate the frequency components that are of interest. The use of RF mixers is well documented, e.g. [27], and detailed reference designs for receivers are publicly available, e.g. [25]. A diagram showing the main Functional Units (FU) of such a generic RF receiver is provided in Figure 10.

FU1 – Antennas: A number of sources describe how to build HF antennas for receiving RF signals, e.g. [4, 18]. Unfortunately these concentrate mainly on E-field antennas for radio applications, although some practical construction and tuning tips still prove useful. The simplest option for building a magnetic antenna is to implement one of the reference designs from TI’s Antenna Cookbook [33], since most of the matching components and construction material are already specified. Alternatively, any form of loop antenna can be implemented and then matched using the guidelines in [34]. It should be noted that these guidelines specify components with a higher power rating, since the antennas are also intended for transmitting. When the antennas are only used to receive signals, components with less stringent power requirements can be used. Enameled copper wire and adhesive copper tape can easily be used to construct HF loop antennas of different sizes and number of loops. An antenna made with adhesive copper tape wire

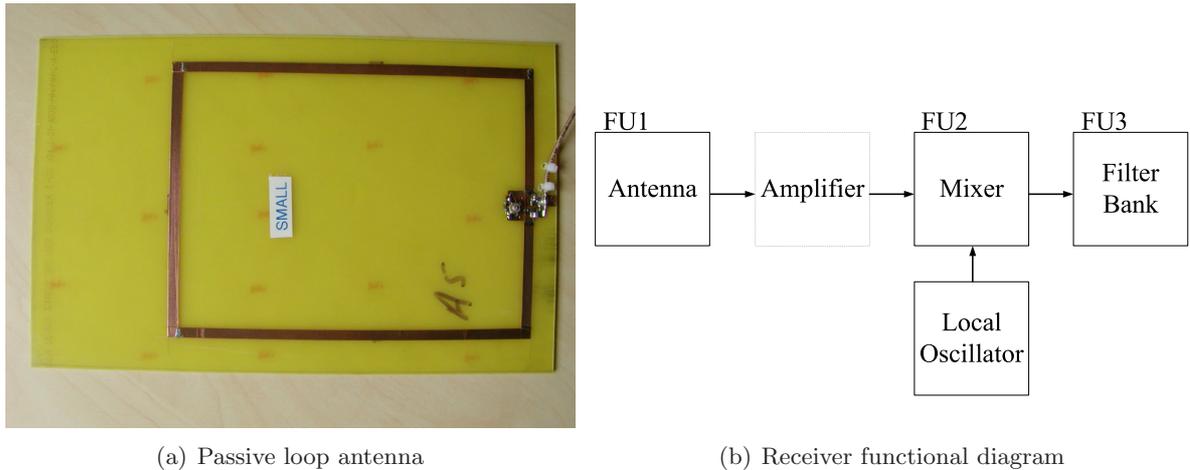


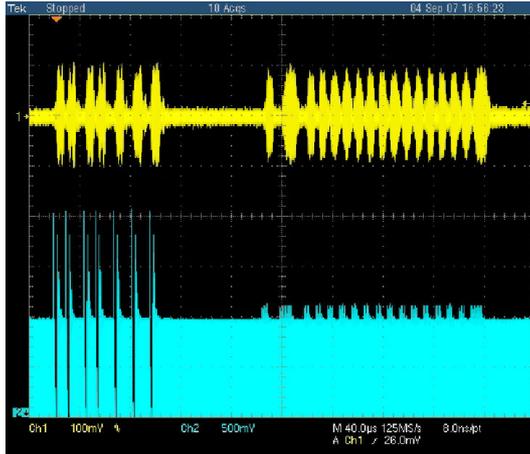
Figure 10: Components of an eavesdropping receiver

is shown in Figure 10(a). The resonant antenna also acts as a crude bandpass filter around the chosen center frequency. The width of the passband can be adjusted by changing the Q-factor.

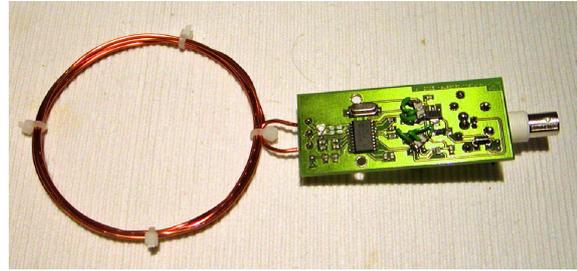
FU2 – Mixer: An optional amplifier stage can be added between the antenna and the mixer. The amplifier’s gain depends on the intended range of the receiver, i.e. short range protocol analyzer or longer range eavesdropping, although it should be kept in mind that most commercial mixer ICs expect an input signal with smaller amplitude and some ICs also have integrated amplifiers. The mixer’s function is to move a spectral band of interest to a chosen intermediate frequency (IF) through direct downconversion. Normally, the advantage of IF systems is that any input signal can be moved to a single IF frequency by using an adjustable mixing frequency, which simplifies the design of the filter bank. In our case the local oscillator’s frequency can be fixed, but using an IF still simplifies the filter implementation since this allows the use of off-the-shelf filters designed for other applications. It is also possible to implement zero-IF receivers that mixes the input down to the baseband (0 Hz). A lowpass filter can then be used to remove the unwanted high frequency components.

FU3 – Filter bank: Filtering helps to isolate the data of interest and remove unwanted frequency components. The filter bank implementation depends on the IF chosen. Choosing an IF that is often used in radio systems, like 10.7 MHz, simplifies the implementation since suitable filters can be purchased. If the system needs to work at another IF it will require the design of custom filters. Information on filter design and relevant tools can be found from most of the large semiconductor manufacturers, e.g. [1, 20, 32]. It should be noted that both passive and active high-frequency filters are sensitive to stray capacitance, or inductance, introduced by the circuit layout. The operational amplifiers selected for use in the active filters must also have adequate slew rate and gain bandwidth to function at the chosen IF.

It is possible to design and construct an RF receiver that could be used to observe both the forward and backward communication of an HF RFID system for less than £50. Figure 11(a) shows an example of ISO 14443A data recovered with an RF receiver, based on an existing design [25], shown in Figure 11(b). The receiver mixes the 14.40 MHz upper sideband down to an IF of 10.7 MHz before using a 500 kHz band-pass filter to recover the sideband data and attenuate the strong carrier. The filter also passes some higher harmonics of the forward channel data. The forward channel pulse shapes are distorted although they are still in the correct position, which is enough information to recover the data in this case. This receiver did not achieve the same results as the commercial RF receiver but we managed to recover



(a) Trace of ISO 14443A REQA command



(b) Inexpensive RF receiver

Figure 11: Details of a homemade eavesdropping kit

the communication on both the forward and backward channels at a range of 60 cm, with no additional amplifier between the antenna and mixer and an antenna of 10 cm radius. However, it shows that even a cash-strapped attacker can construct a suitable receiver that could be used in a real attack. In reality one should assume that an attacker may have more resources available, in other words he might be in the position to purchase commercial RF equipment.

3.4.2 Signal capture and demodulation

The attacker needs to capture and demodulate the signal from his receiver. The sampling rate used by the attacker is dependent on the output of his receiver, since the rate needs to be at least twice the highest frequency component of the output to prevent aliasing effects. For example, if he used a zero IF receiver with a 1 MHz low pass filter he would need to sample at 2 MHz. An attacker can choose to make a recording and perform data recovery later or implement a real-time demodulator/decoder using a fast enough FPGA or DSP device. If the attacker chose to store a recording the amount of memory needed will depend on the sampling rate chosen. For example, an attacker taking 8-bit samples at a rate of 2 MHz for 10 s would need 20 MB of memory to store each recording. This would be higher if he uses oversampling or if he needs to sample a higher IF output. These requirements are not unrealistic taken into account that an attacker can acquire suitable hardware for a few £100, since most Field Programmable Gate Arrays (FPGA) or Digital Signal Processing (DSP) development kits come with the necessary Random Access Memory (RAM) and Analog-to-Digital Converters (ADC).

4 Skimming

The skimming attack occurs when an unauthorized reader gains access to data stored on a token. In this attack scenario an attacker tries to read the token without the victim knowing. As is the case with eavesdropping, there are different skimming distances to consider. The attacker needs to provide power and send commands to the token, which he can achieve at a distance of D_P . The attacker then needs to recover the token's response, which is the same as recovering the backward channel, so this distance is defined as D_{EB} . D_P is the furthest distance from the reader that a card still powers up and interprets a command, not the distance the token must

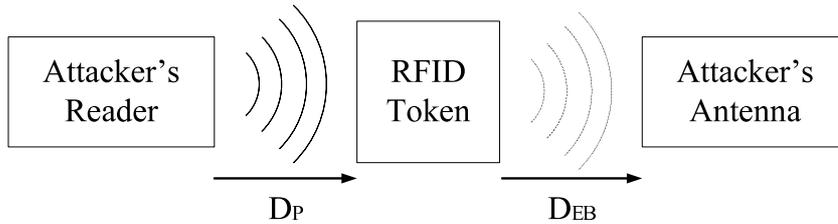


Figure 12: Different distance parameters for a skimming attack

be from the reader to allow an attacker to recover the response. If there is a single attacker the overall skimming distance is $\min(D_P, D_{EB})$.

Ideally, an attacker must increase the operational range of his reader to avoid raising suspicion. Increasing the range is not a new technical challenge and methods for doing this are in fact described in application notes by several RFID chip manufacturers, e.g. Texas Instruments [34] and ST Microelectronics [44]. The range can be extended simply by enlarging the antenna and increasing the transmitted power of the reader. An attacker, however, does have an additional advantage in executing an attack since he is not bounded by the same transmission limits [45] adhered to by industry designers.

Since most of the application notes for increasing the operational range described a reader with a single antenna, we wanted to investigate an alternative skimming setup with two antennas. This scenario was briefly mentioned in [10] but not fully investigated or explained in detail. In this scenario one attacker has a modified reader that activates and commands the token, while the second attacker has commercial eavesdropping equipment to recover the response. The reason we proposed this setup was that it allowed the attackers some flexibility when deciding on which antennas to use. For example, they could conceal a small loop antenna, which works well for power coupling close to the target token. A larger H-field RF antenna designed purely for receiving, such as the Dynamic Sciences H-field antenna, can then be placed further away to recover the response. We wanted to test whether this setup could achieve a greater distance D_{EB} when compared to the single antenna attack, usually mentioned in literature [37] [35].

4.1 Experimental setup

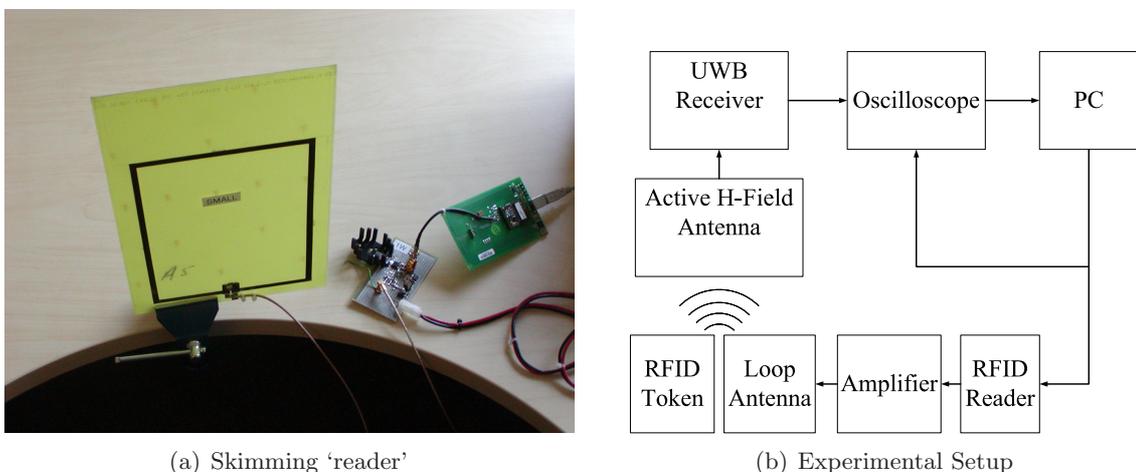


Figure 13: Setup of the skimming experiment

The RF equipment and the environment is the same as described in Section 3.1. The only

difference is the reader, which has been fitted with an amplifier and a larger antenna, and the position of the token, which is now attached to a wooden stand at the same height as the reader’s antenna. We tested the attack with an ISO 14443A compliant Mifare Classic token. The attack setup is shown in Figure 13.

4.1.1 Skimming reader

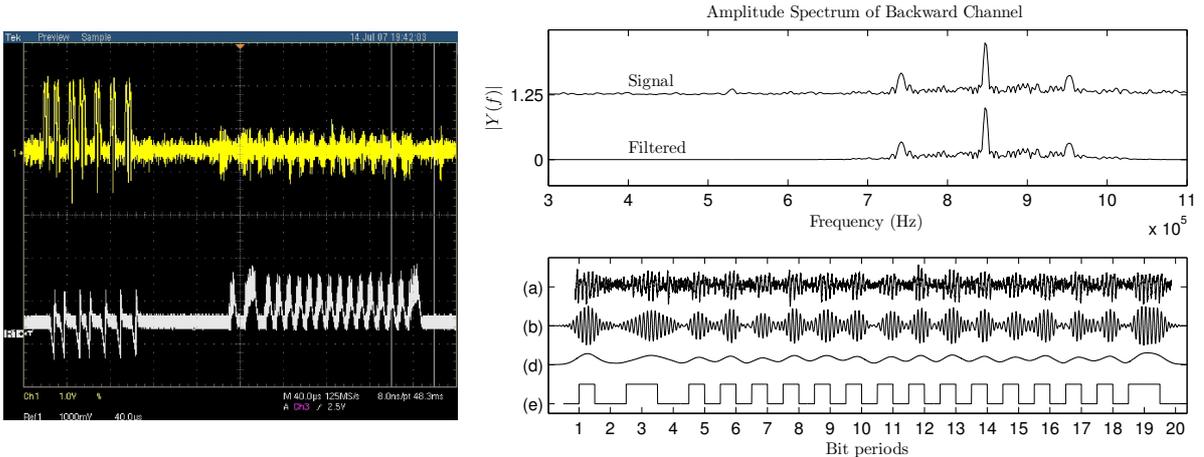
We connected the output signal of the ACG Multi-ISO reader to a power amplifier and transmitted it to the card using a copper tape loop antenna. We used four amplifiers and three copper-tape loop antennas of different sizes. The amplifiers are class E, so they are efficient for narrow-band signals and therefore well suited to RFID applications. A reference design for this class of amplifier, used to extend the range of an ST Microelectronic near-field coupling IC, is shown in [44]. We already discussed the construction of loop antennas in Section 3.4. The antennas were designed for $Q \approx 5$ and capacitive matching was used to tune the antennas to the required center frequency.

4.1.2 Pick-up coil

To test whether a token had been powered and received the data correctly we used a pick-up coil in close proximity to see if it generated the correct response. It is not sufficient to use the eavesdropping system as in some cases no response can be detected even though the token did respond. The pick-up coil we used consisted of a small, tuned copper loop antenna and an envelope detector, which allowed me to quickly determine the value of D_P .

4.2 Method

We first used the pick-up coil to determine the maximum activation distance D_P that can be achieved with different combinations of reader amplifiers and antennas. This was done by systematically moving the token further away from the reader in 1 cm increments and checking with the pick-up coil, held against the token, whether the token responds. We assumed that the token was sufficiently powered and successfully received a command from the reader if the token provided a valid response. We then left the token at this distance from the reader and tried to recover the backward channel data with the eavesdropping system. If we failed to recover the response data the token would be moved closer to the reader in steps of 1 cm until we could recover the token’s response with the H-field eavesdropping antenna placed 10 cm away from the token. We chose 10 cm as a starting distance as it is the advertised operating range for ISO 14443 systems and we felt that skimming could only be deemed successful if demonstrated beyond this distance. If we succeeded in recovering the response the eavesdropping antenna would be placed further away, in multiples of 20 cm, until we failed to recover the token’s response. After some initial experimentation, we estimated D_P to be in the 0–30 cm range and following on from our eavesdropping results we expected D_{EB} to be in the 0–400 cm range. For this reason, we chose the distance increments for the eavesdropping antenna to be larger than the distance increments for the token from the reader. Once we failed to recover the response the token was again moved closer to the reader and the process was repeated. An example of the eavesdropped signal, the pick-up coil reference and the data recovery is shown in Figure 14. We performed the experiment with all the different combinations of antennas and amplifiers. The reference data, signal capture method and data recovery steps are the same as those described for eavesdropping of the backward channel in Section 3.2.



(a) A5 antenna with 1 W amplifier, $D_P = 15$ cm and $D_{EB} = 2$ m

(b) Frequency spectrum and data recovery

Figure 14: Example of skimming results showing the time signal trace, the frequency spectrum and the recovered data

4.3 Results

The maximum distance D_P for each combination of antenna and amplifier is shown in Table 2. D_P increases as the antenna size and the transmitted power increases, which was the expected result.

	0.5 W	1 W	2 W	4 W
148×210 mm ($\frac{1}{32}$ m ²)	15 cm	16 cm	17 cm	19 cm
210×297 mm ($\frac{1}{16}$ m ²)	20 cm	23 cm	23 cm	25 cm
297×420 mm ($\frac{1}{8}$ m ²)	22 cm	25 cm	26 cm	27 cm

Table 2: Maximum D_P for each antenna/amplifier setup

The best result for D_{EB} was 2 m, obtained using the 14.8×21 cm antenna with the 1 W amplifier when D_P was 15 cm. We expected D_{EB} to increase in the same way as D_P did. Instead the distance at which we could retrieve the response actually decreased. This could possibly be attributed to a number of factors:

- The amplitude of the load modulation appeared constant and not proportional to the amplitude of the carrier signal, so essentially the modulation index was decreased each time the amplitude of the carrier was increased. This is possibly due to current limiting incorporated in the token’s power supply design. The token modulates data onto the carrier using “load modulation”, i.e. the carrier amplitude changes when the impedance of the token is modified and the amount of current that it draws changes. If the carrier amplitude is increased the token needs to attenuate the carrier more to maintain the modulation index, which means that it would need to draw more current. Current limiting protects the token’s circuitry but also prevents it from sinking the current required.
- As the token was moved further from the antenna the effect of its coupling decreased. The effect of the load modulation therefore decreased as D_P increased and even though the token could be activated at greater distances the token had to be moved closer to influence the field of the antenna.

This negated the advantage of larger antenna/amplifier combinations. With the largest antenna D_P and D_{EB} were approximately equal to 20 cm. This was the largest value of D_P at which we managed to retrieve the backward channel. When $D_P \approx D_{EB}$ the attacker gains no advantage from using two different antennas. In fact, the two antenna method offers no distance advantage over the method using only one antenna, achieving comparable results to the single antenna scenario demonstrated in [37], and approaching the theoretical limit stated in [35]. It is, however, an attractive alternative if the attacker needs to limit the size of his hardware. In the two antenna case he can use a smaller antenna, with a less powerful amplifier, while placing his signal capturing equipment much further away. In [37] the skimming range of 25 cm was achieved using an antenna 40 cm in diameter. Arguably an attacker can better conceal a 14.8×21 cm antenna, which is half the diameter, which allows him to hold it closer to his target while an accomplice sits up to 2 m away recovering the token’s response. The threat of the skimming attack seemed slightly diminished as D_P ended up quite small for the best case of D_{EB} . That said, 15 or 20 cm is probably enough to execute an attack in a crowded area and easily allows reading of a token in somebody’s pocket or bag.

5 Conclusion

HF RFID devices using near-field communication are used in a number of secure application such as e-passports and credit cards. The RF communication interface of these devices are vulnerable to eavesdropping and skimming attacks. These attacks are a well known risk for RFID devices, yet few publications give details about possible experimental setup or practical results.

In this paper we present results from practical proof-of-concept eavesdropping and skimming attacks implemented against HF RFID devices. We successfully performed eavesdropping attacks against devices implementing the three most popular HF standards: ISO 14443A/B and ISO 15693. We also present results of a skimming attack method where the attackers use two separate antennas to power the token and retrieve its response, unlike most skimming attacks that use a single antenna. In each case we describe the equipment needed and document the attack setup and execution. We also describe the implementation of an RFID receiver kit that could be constructed for less than £50, which can be used to observe RFID communication. Even though the self-build RF receiver did not achieve the same results as commercial equipment it does illustrate that eavesdropping is not beyond the means of the average attacker.

Eavesdropping attacks are dependent on a variety of factors so someone else with different RF equipment and environmental conditions might achieve a different result. In the attacker’s perfect world, or with ‘advanced monitoring equipment and ideal environmental conditions, including optical line of sight transmission, low humidity, and no radio interference’, to quote [21], eavesdropping could be possible at much greater distances as is indeed shown to be the case in [9]. Our main contribution was therefore not so much the actual attack distances, but rather the experimental setup that provides other researchers with a reference attack, which they can study and improve upon. That said, our results do confirm that near-field devices are not rigidly location limited and that an attacker can definitely recover data beyond the advertised operating range. It also provides a practical result to debate, which is important for RFID technology where attack distances are so often seen as a measure of security. By demonstrating practical eavesdropping and skimming techniques we hope to promote a better understanding of these attacks. In turn we hope that our work will assist system designers to better comprehend the eavesdropping threat in order to select appropriate technologies and countermeasures.

There is still scope for further work on RFID eavesdropping and skimming, such as testing the effect that different reader designs have on eavesdropping distance and developing better data recovery methods. For example, what eavesdropping distances would be possible on NFC-enabled mobile phones when communicating in passive and active configurations. We started

doing some preliminary work on testing how the tuning of the reader and the token affects the eavesdropping range. For example, we placed the antenna 1 m away from the reader and displayed the AM demodulated output of the RF receiver on the oscilloscope. By changing the parallel tuning capacitor value on the reader the amplitude of the backward channel data recovered by the receiver could be largely reduced. This also decreases the operational distance, although this might be an acceptable sacrifice to limit the risk of eavesdropping. We have also not yet looked at using E-field antennas to eavesdrop on the communication between the reader and the token, or considered whether there is data inadvertently transmitted in other frequency bands.

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